

1- The following code solves the problem.

```
#include "uart_transmitter.h"

typedef enum{idle, transmit} uart_transmit_states_type;

void uart_transmitter(bool &uart_tx, ap_uint<8> data, bool
baud_rate_signal, bool start) {
#pragma HLS INTERFACE ap_none port=data
#pragma HLS INTERFACE ap_none port=baud_rate_signal
#pragma HLS INTERFACE ap_none port=uart_tx
#pragma HLS INTERFACE ap_none port=start
#pragma HLS INTERFACE ap_ctrl_none port=return

    bool even_parity = data.xor_reduce();
    ap_uint<12> d = ((ap_int<2>)1, (bool)even_parity, (ap_int<8>)data,
(bool)0b0);

    static unsigned int          bit_counter = 0;
    static uart_transmit_states_type state = idle;

    uart_transmit_states_type next_state;
    unsigned int              next_bit_counter;
    bool uart_tx_local;

    switch(state) {
    case idle:
        if ( start == 1) {
            next_state = transmit;
            uart_tx_local = 1;
            next_bit_counter = 0;
        } else {
            next_state = idle;
            uart_tx_local = 1;
            next_bit_counter = 0;
        }
        break;
    case transmit:
        if (baud_rate_signal == 1) {
            if (bit_counter == 12) {
                next_state = idle;
                uart_tx_local = 1;
                next_bit_counter = 0;
            } else {
                next_state = transmit;
                uart_tx_local = d[bit_counter];
                next_bit_counter = bit_counter+1;
            }
        } else {
            if (bit_counter == 0) {
```

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        uart_tx_local    = 1;
    } else {
        uart_tx_local    = d[bit_counter-1];
    }
    next_state          = transmit;
    next_bit_counter    = bit_counter;
}

break;

default:
    break;
}

state                = next_state;
bit_counter          = next_bit_counter;
uart_tx              = uart_tx_local;
}

```

- 2- To cope with this problem, we should modify the baud rate generator and the UART receiver IPs. The following codes show these modifications.

```

//9600 baud rate --> BAUD_RATE_NUMBER = (1s/14400)/10ns =
(1000000000/14400)/10 = 6944
#define BAUD_RATE_NUMBER 6944

//for simulation
//#define BAUD_RATE_NUMBER 20

typedef enum{zero, one} baud_rate_states_type;
void baud_rate_generator(bool &baud_rate_signal) {
#pragma HLS INTERFACE ap_none port=baud_rate_signal
#pragma HLS INTERFACE ap_ctrl_none port=return

    static baud_rate_states_type state = zero;
    static unsigned int counter = BAUD_RATE_NUMBER-1;

    baud_rate_states_type next_state;
    unsigned int next_counter;

    bool baud_rate_signal_local;

    switch(state) {
    case zero:
        if (counter == 1) {
            next_counter    = counter-1;
            next_state      = one;

```

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        } else {
            next_counter      = counter-1;
            next_state        = zero;
        }
        baud_rate_signal_local = 0;
        break;
    case one:
        next_counter          = BAUD_RATE_NUMBER-1;
        next_state            = zero;
        baud_rate_signal_local = 1;

        break;
    default:
        break;
}

state = next_state;
counter = next_counter;
baud_rate_signal = baud_rate_signal_local;
}

```

```

typedef enum{idle, receive} uart_receive_states_type;

void uart_receiver (bool uart_rx, bool baud_rate_signal, ap_uint<8> &data, bool
&valid_data) {
#pragma HLS INTERFACE ap_none port=valid_data
#pragma HLS INTERFACE ap_none port=data
#pragma HLS INTERFACE ap_none port=baud_rate_signal
#pragma HLS INTERFACE ap_none port=uart_rx
#pragma HLS INTERFACE ap_ctrl_none port=return

    static ap_uint<8> d;
    static unsigned int bit_counter = 0;
    static uart_receive_states_type state = idle;

    uart_receive_states_type next_state;
    unsigned int next_bit_counter ;

    bool stop_bit;
    bool odd_parity_bit;
    bool valid_data_local = 0;

    switch(state) {
    case idle:
        if (baud_rate_signal == 1) {
            if (uart_rx == 0) {
                next_state = receive;
            }
        }
    }
}

```

```
        } else {
            next_state = idle;
        }
    } else {
        next_state = idle;
    }
    valid_data_local = 0;
    next_bit_counter = 0;
    break;
case receive:
    if (baud_rate_signal == 1) {
        if (bit_counter == 9) {
            stop_bit = uart_rx;
            if (stop_bit == 1) {
                valid_data_local = 1;
            } else {
                valid_data_local = 0;
            }
            next_bit_counter = bit_counter+1;
            next_state = idle;
        } else if (bit_counter == 8) {
            odd_parity_bit = uart_rx;
            if (odd_parity_bit == !d.xor_reduce()) {
                valid_data_local = 1;
            } else {
                valid_data_local = 0;
            }
            next_bit_counter = bit_counter+1;
            next_state = idle;
        } else {
            d[bit_counter] = uart_rx;
            next_bit_counter = bit_counter+1;
            next_state = state;
            valid_data_local = 0;
        }
    } else {
        valid_data_local = 0;
        next_state = receive;
        next_bit_counter = bit_counter;
    }
    break;
default:
    break;
}

state = next_state;
bit_counter = next_bit_counter;
data = d;
valid_data = valid_data_local;
}
```